

# AI-501 Mathematics for AI

## Singular Value Decomposition and Spaces

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[https://www.zubairkhalid.org/ai501\\_2024.html](https://www.zubairkhalid.org/ai501_2024.html)

# Outline

- *Eigenvalue Decomposition*
  - *Eigenvectors, Eigenvalue overview*
  - *Formulation*
  - *Interpretation*

# Eigenvalue Decomposition (EVD)

## Eigenvectors and Eigenvalues:

For square matrices, *eigenvectors* and *eigenvalues* are vectors and numbers represent the *eigen-decomposition* of a matrix; analyzes the structure of this matrix.

For a matrix  $A \in \mathbf{R}^{n \times n}$

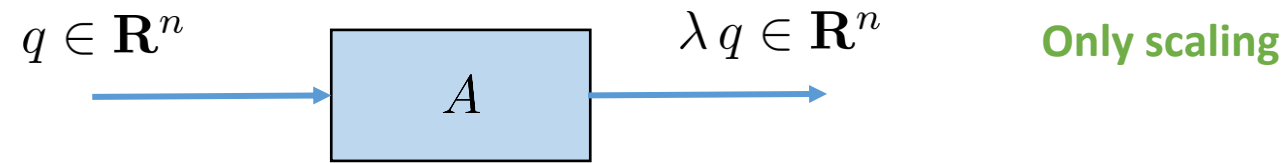
a vector  $q \in \mathbf{R}^n$ ,  $q \neq 0$ , is called an eigenvector of  $A$  if

$$Aq = \lambda q \quad \text{Eigenvalue Equation}$$

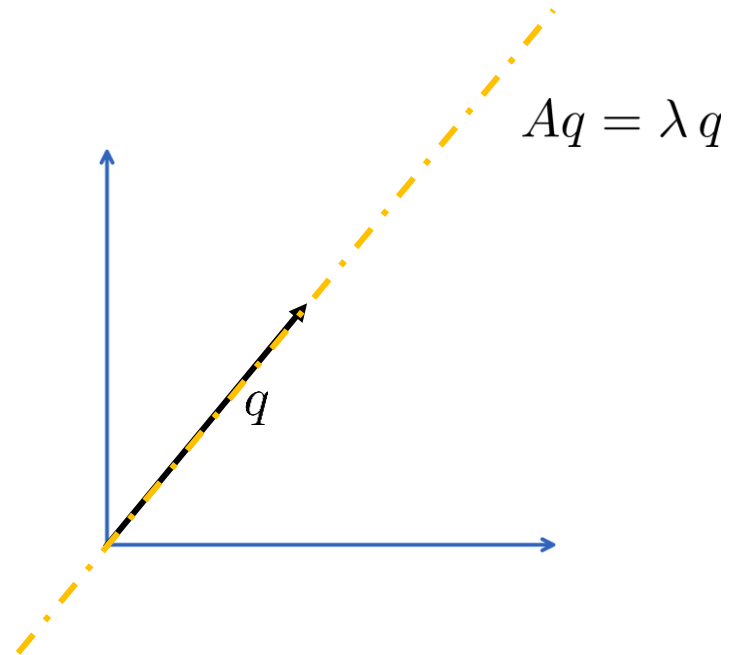
-  $\lambda$  is referred to as an eigenvalue of  $A$  associated with the eigenvector  $q$

# Eigenvalue Decomposition (EVD)

Linear transformation interpretation:



Graphically



# Eigenvalue Decomposition (EVD)

## Eigenvectors and Eigenvalues:

How to compute eigenvalues?

$$Aq = \lambda q \quad \Rightarrow \quad Aq - \lambda q = 0$$

$$p(\lambda) = \det(Aq - \lambda q) = 0 \quad \text{Characteristic polynomial; degree } n$$

$n$  eigenvalues

Eigenspectrum: set of eigenvalues

$n$  eigenvectors

Eigenspace: span of eigenvectors

# Eigenvalue Decomposition (EVD)

## Eigenvectors and Eigenvalues:

$$Aq = \lambda q$$

$n$  eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_n$

$n$  eigenvectors  $q_1, q_2, \dots, q_n \in \mathbf{R}^n$

$$Aq_1 = \lambda_1 q_1, \quad Aq_2 = \lambda_2 q_2, \quad \dots$$

$$AQ = Q\Lambda$$

$$A = Q\Lambda Q^{-1}$$

Eigen-decomposition

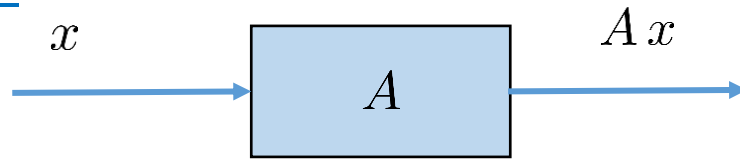
$$\Lambda = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix}$$

$$Q = \begin{bmatrix} (q_1)_1 & (q_2)_1 & \dots & (q_n)_1 \\ (q_1)_2 & (q_2)_2 & \dots & (q_n)_2 \\ \vdots & \vdots & \ddots & \vdots \\ (q_1)_n & (q_2)_n & \dots & (q_n)_n \end{bmatrix}$$

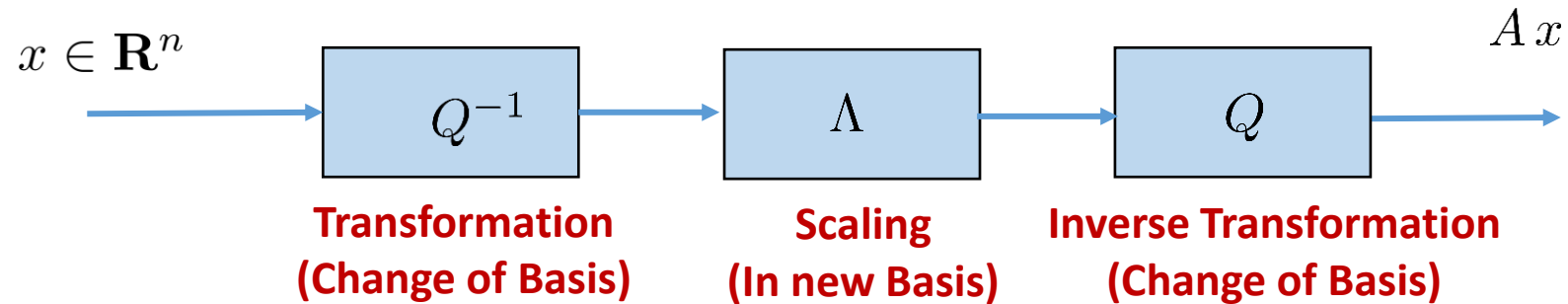
# Eigenvalue Decomposition

What does eigenvector and eigenvalues reveal about A?

Linear Transformation

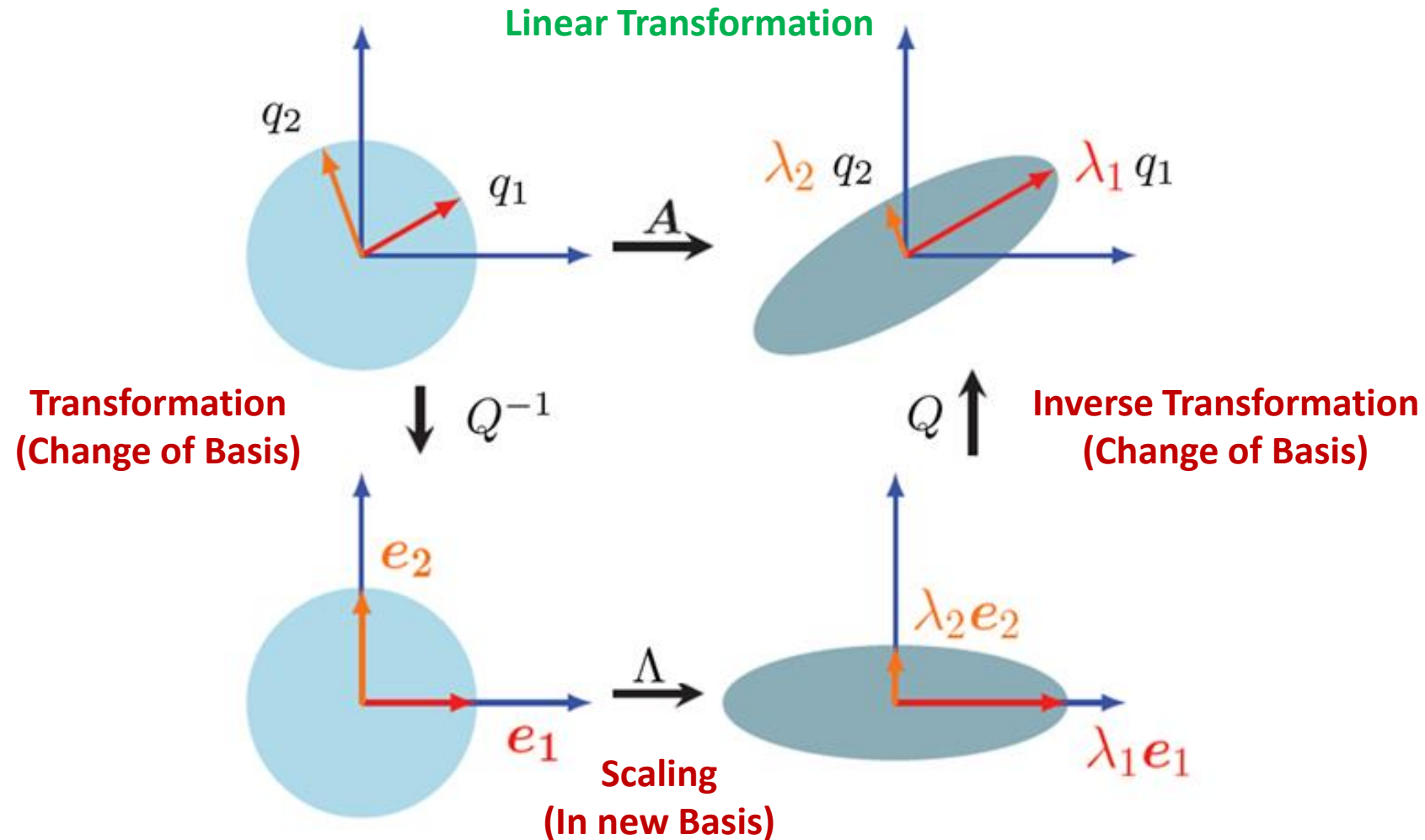


Linear Transformation Interpretation in terms of Eigen-decomposition of the Matrix



# Eigenvalue Decomposition

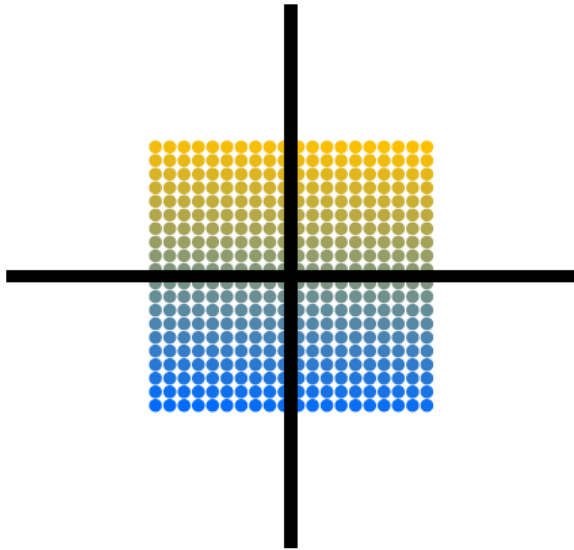
## Linear Transformation Interpretation in terms of Eigen-decomposition of the Matrix - Visualization





# Eigenvalue Decomposition

## Eigen-decomposition of the Matrix - Example

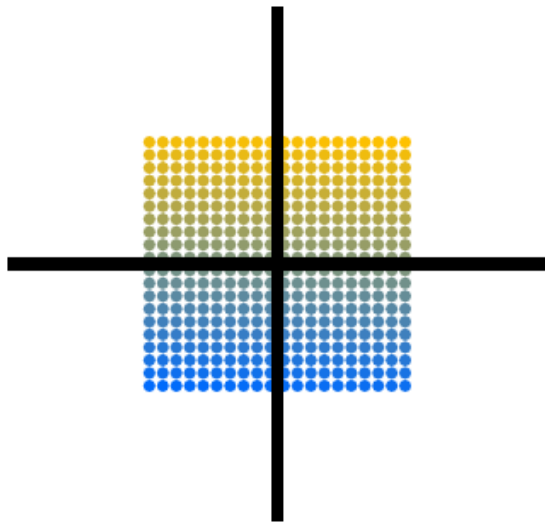


$$\lambda_1 = 2.0$$
$$\lambda_2 = 0.5$$
$$\det(\mathbf{A}) = 1.0$$

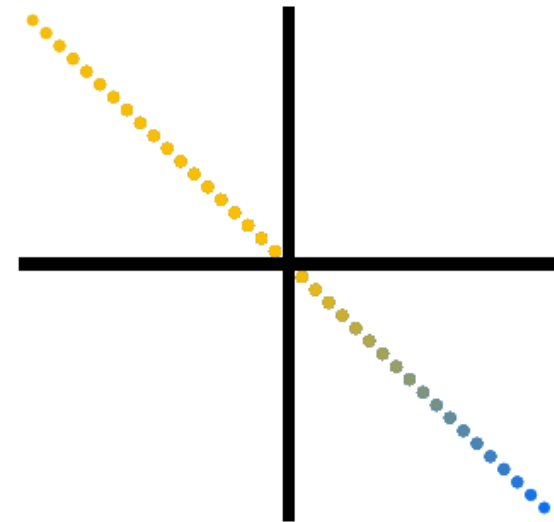
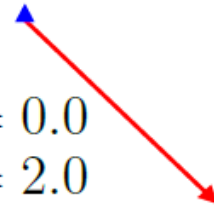


# Eigenvalue Decomposition

## Eigen-decomposition of the Matrix - Example



$$\lambda_1 = 0.0$$
$$\lambda_2 = 2.0$$
$$\det(\mathbf{A}) = 0.0$$



# Eigenvalue Decomposition

## Determinant in terms of Eigenvalues

- Determinant of a matrix  $A \in \mathbf{R}^{n \times n}$  is given by the product of eigenvalues, that is,

$$\det(A) = \det(Q\Lambda Q^{-1}) = \det(Q) \det(\Lambda) \det(Q^{-1})$$

$$\det(A) = \det(Q\Lambda Q^{-1}) = \det(Q) \left( \prod_{i=1}^n \lambda_i \right) \frac{1}{\det(Q)}$$

$$\det(A) = \prod_{i=1}^n \lambda_i$$

- If one of the eigenvalues is zero, determinant of the matrix is zero.
  - I encourage you to connect this with the interpretation of determinant and (eigenvectors, eigenvalues).

# Eigenvalue Decomposition (EVD)

## EVD of Inverse Matrix:

- Matrix inverse  $A^{-1}$  has same eigenvectors but eigenvalues are given by inverse of the eigenvalues of the original matrix  $A$ .
- This can be shown in multiple ways. Let's use eigenvalue equation to show this.

For a matrix  $A \in \mathbf{R}^{n \times n}$

$$Aq = \lambda q \quad \text{Eigenvalue Equation}$$

- Assuming  $A$  is invertible, that is, all eigenvalues are non-zero.

$$A^{-1}Aq = \lambda A^{-1}q \quad \frac{1}{\lambda}q = A^{-1}q$$

This implies  $q$  is an eigenvector of  $A^{-1}$  with associated eigenvalue  $\frac{1}{\lambda}$ .

# Eigenvalue Decomposition

## Power of a matrix

$$AA = A^2 = Q\Lambda Q^{-1} Q\Lambda Q^{-1} = Q\Lambda^2 Q^{-1}$$

$$A^n = Q\Lambda^n Q^{-1}$$

- I encourage you to connect this with the interpretation of linear transformation using EVD of a matrix.

# Eigenvalue Decomposition

## Zero eigenvalues; Columns of A are not linearly independent

- If one of the eigenvalues is zero and  $q$  is an associated eigenvector.

$$Aq = \lambda q = 0$$

- It simply follows from the definition of linear independence that the columns are not linearly independent since  $Aq$  represents the linear combination of columns of  $A$ .

# Eigenvalue Decomposition

## Eigenvalues of a Symmetric Matrix

- (Spectral Theorem) For a symmetric matrix  $A \in \mathbf{R}^{n \times n}$ , there exists an orthonormal basis of the corresponding vectors space consisting of eigenvectors of  $A$  and each eigenvalue is real.

$$A = Q \Lambda Q^{-1}$$

Since  $A = A^T$ , we have  $(Q^{-1} = Q^T$

$$A^T = (Q^{-1})^T \Lambda Q^T$$

↓  
Orthonormal matrix

- Summary: For a symmetric matrix, eigenvectors are orthonormal and eigenvalues are real.

# Outline

- *Positive/negative definite and semi-definite matrices*
- *Singular Value Decomposition (SVD)*
  - *Formulation*
  - *Interpretation*
  - *Application examples*
- *Column space and Null Space*



# Positive/Negative Definite/Semi-Definite Matrices

## Definition:

For a matrix  $A \in \mathbf{R}^{n \times n}$ , if

$$x^T A x \geq 0 \quad \forall x \in \mathbf{R}^n \quad A \text{ is positive semi-definite (PSD)}$$

$$x^T A x > 0 \quad \forall x \in \mathbf{R}^n \quad A \text{ is positive definite (PD)}$$

$$x^T A x \leq 0 \quad \forall x \in \mathbf{R}^n \quad A \text{ is negative semi-definite (NSD)}$$

$$x^T A x < 0 \quad \forall x \in \mathbf{R}^n \quad A \text{ is negative definite (ND)}$$

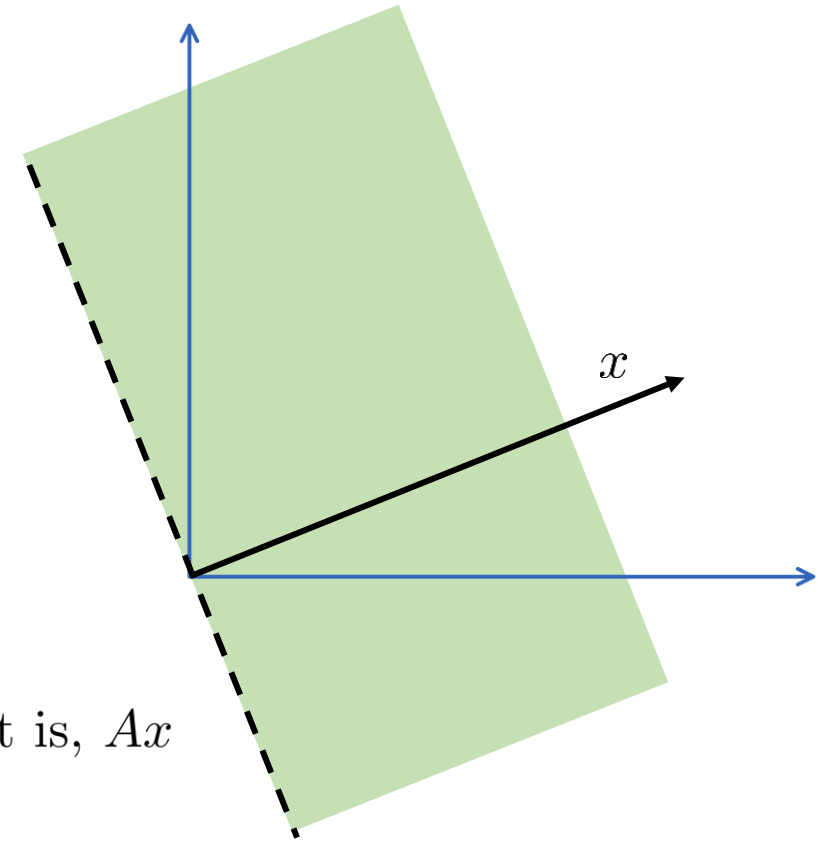
# Positive Definite and Semi-Definite Matrices

## Interpretation:

$A$  is positive semi-definite (PSD)

$$x^T A x \geq 0$$

- Let  $y = Ax$ 
  - $y$  is a linear transformation defined by the matrix  $A$ .
- $x^T y \geq 0$  implies angle between  $x$  and  $y$  is less than or equal to  $\frac{\pi}{2}$ .
- $x^T y \geq 0$  implies angle between  $x$  and linearly transformed  $x$ , that is,  $Ax$  is less than or equal to  $\frac{\pi}{2}$ .



Graphically, a vector  $x$  when transformed by a matrix  $A$ , that is,  $Ax$  can be anywhere in the green region including the dashed boundary where  $x^T A x = 0$

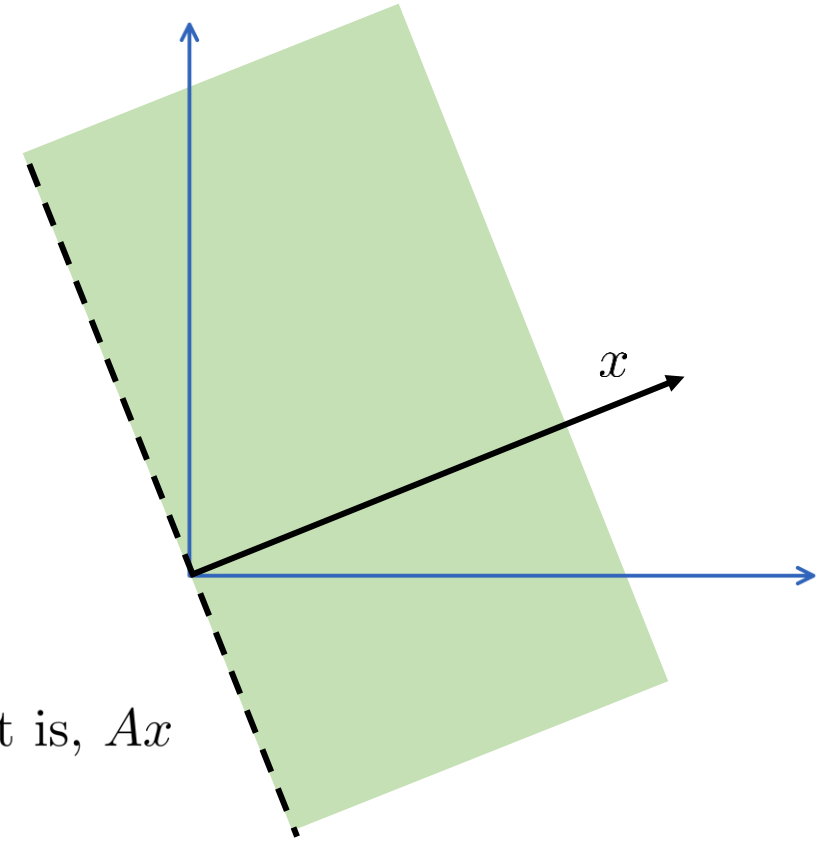
# Positive Definite and Semi-Definite Matrices

## Interpretation:

$A$  is positive definite (PD)

$$x^T A x > 0$$

- Let  $y = Ax$ 
  - $y$  is a linear transformation defined by the matrix  $A$ .
- $x^T y > 0$  implies angle between  $x$  and  $y$  is less than  $\frac{\pi}{2}$ .
- $x^T y \geq 0$  implies angle between  $x$  and linearly transformed  $x$ , that is,  $Ax$  is less than  $\frac{\pi}{2}$ .



Graphically, a vector  $x$  when transformed by a matrix  $A$ , that is,  $Ax$  can be anywhere in the green region excluding the dashed boundary where  $x^T A x = 0$

# Positive Definite and Semi-Definite Matrices

## Eigenvalues of symmetric PSD/PD matrix:

For a symmetric and PD matrix  $A$ , eigenvalues are positive.

### How?

- We already know that the eigenvalues of a symmetric matrix are real.
- For a PD symmetric, we require  $x^T Ax > 0$
- If we take  $x = q$ , where  $q$  is an eigenvector with an associated eigenvalue

$\lambda$

$$q^T Aq > 0 \Rightarrow \lambda q^T q > 0 \Rightarrow \lambda \|q\|_2^2 > 0 \Rightarrow \lambda > 0$$

### Similarly, we can show the following:

For a symmetric and PSD matrix  $A$ , eigenvalues are non-negative.

For a symmetric and NSD matrix  $A$ , eigenvalues are non-positive.

For a symmetric and ND matrix  $A$ , eigenvalues are negative.

# Outline

- Positive/negative definite and semi-definite matrices
- Singular Value Decomposition (SVD)

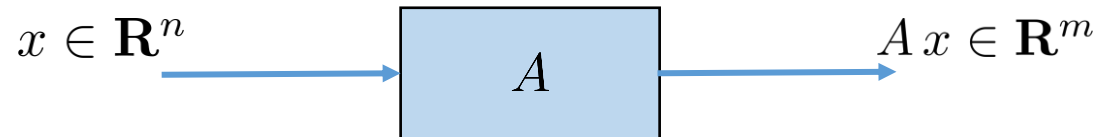
# Outline

- Positive/negative definite and semi-definite matrices
- Singular Value Decomposition (SVD)
  - Formulation
  - Interpretation
  - Application examples
- Column space and Null Space

# Singular Value Decomposition

## Overview:

- The singular value decomposition (SVD) of a matrix is a central matrix decomposition method in linear algebra.
- It has been referred to as the “fundamental theorem of linear algebra” (Strang, 1993) because it can be applied to all matrices, not only to square matrices, and it always exists.
- For  $A \in \mathbf{R}^{m \times n}$ , we have



- SVD explains the underlying geometry of this linear transformation.

# Singular Value Decomposition

## Formulation:

- For any matrix  $A \in \mathbf{R}^{m \times n}$ , we have a singular value decomposition (SVD) given by

$$A = U \Sigma V^T$$

- Matrix  $U \in \mathbf{R}^{m \times m}$  is an orthonormal matrix.
- Matrix  $V \in \mathbf{R}^{n \times n}$  is an orthonormal matrix.
- Matrix  $\Sigma \in \mathbf{R}^{m \times n}$  is a (special) diagonal matrix.

$$\Sigma = \begin{bmatrix} \sigma_1 & 0 & \dots & 0 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & 0 & \dots & 0 \\ 0 & 0 & \dots & \sigma_m & 0 & \dots & 0 \end{bmatrix} \quad m < n$$

$$\Sigma = \begin{bmatrix} \sigma_1 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_n \end{bmatrix} \quad m = n$$

$$\Sigma = \begin{bmatrix} \sigma_1 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_n \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{bmatrix} \quad m > n$$



# Singular Value Decomposition

## Formulation:

$$A = U \Sigma V^T$$

- Columns of  $U$  are referred to as left singular vectors of matrix  $A$ .
- Columns of  $V$  are referred to as right singular vectors of matrix  $A$ .
- $\sigma_1, \sigma_2, \dots, \sigma_{\min(m,n)}$  are singular values of matrix  $A$ , which are (usually) indexed such that

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_{\min(m,n)} \geq 0$$

# Singular Value Decomposition

## How to Compute SVD?

- For a matrix  $A \in \mathbf{R}^{m \times n}$ , we define a matrix  $G = AA^T$ .
- Using  $A = U \Sigma V^T$ , we can write  $G$  as

$$G = U \Sigma V^T V \Sigma^T U^T = U \Sigma \Sigma^T U^T$$

- What is special about matrix  $G$ ?
  - $G$  is symmetric by definition.
  - $G$  is positive semi-definite. How? You are fully equipped to show this.
- We note that  $\Sigma \Sigma^T$  is a diagonal matrix of size  $m \times m$ .
- Eigenvalue decomposition of  $G$  gives columns of  $U$  as eigenvectors and diagonal entries of  $\Sigma \Sigma^T$  as eigenvalues.
- In other words, left singular vectors of  $A$  are eigenvectors of  $AA^T$  and  $\sigma^2 = \lambda$  (eigenvalue of  $AA^T$ ). Furthermore,  $\lambda \geq 0$  since  $G = AA^T$  is PSD.

Eigenvalue decomposition of  $AA^T$  gives  $m$  left singular vectors of  $A$  and first  $m$  singular values.

# Singular Value Decomposition

## How to Compute SVD?

- Now we define a matrix  $G = A^T A$ .
- Using  $A = U \Sigma V^T$ , we can write  $G$  as

$$G = V \Sigma^T U^T U \Sigma V^T = V \Sigma^T \Sigma V^T$$

- What is special about matrix  $G$ ?
  - $G$  is symmetric by definition.
  - $G$  is positive semi-definite. How? You are fully equipped to show this.
- We note that  $\Sigma^T \Sigma$  is a diagonal matrix of size  $n \times n$ .
- Eigenvalue decomposition of  $G$  gives columns of  $V$  as eigenvectors and diagonal entries of  $\Sigma^T \Sigma$  as eigenvalues.
- In other words, right singular vectors of  $A$  are eigenvectors of  $A^T A$  and  $\sigma^2 = \lambda$  (eigenvalue of  $A^T A$ ). Furthermore,  $\lambda \geq 0$  since  $G$  is PSD.

Eigenvalue decomposition of  $A^T A$  gives  $n$  right singular vectors of  $A$  and first  $n$  singular values.

Now you can explain the non-negativity of the singular values.

# Singular Value Decomposition

## SVD Summary

- Singular value decomposition (SVD) of a matrix  $A \in \mathbf{R}^{m \times n}$  is given by

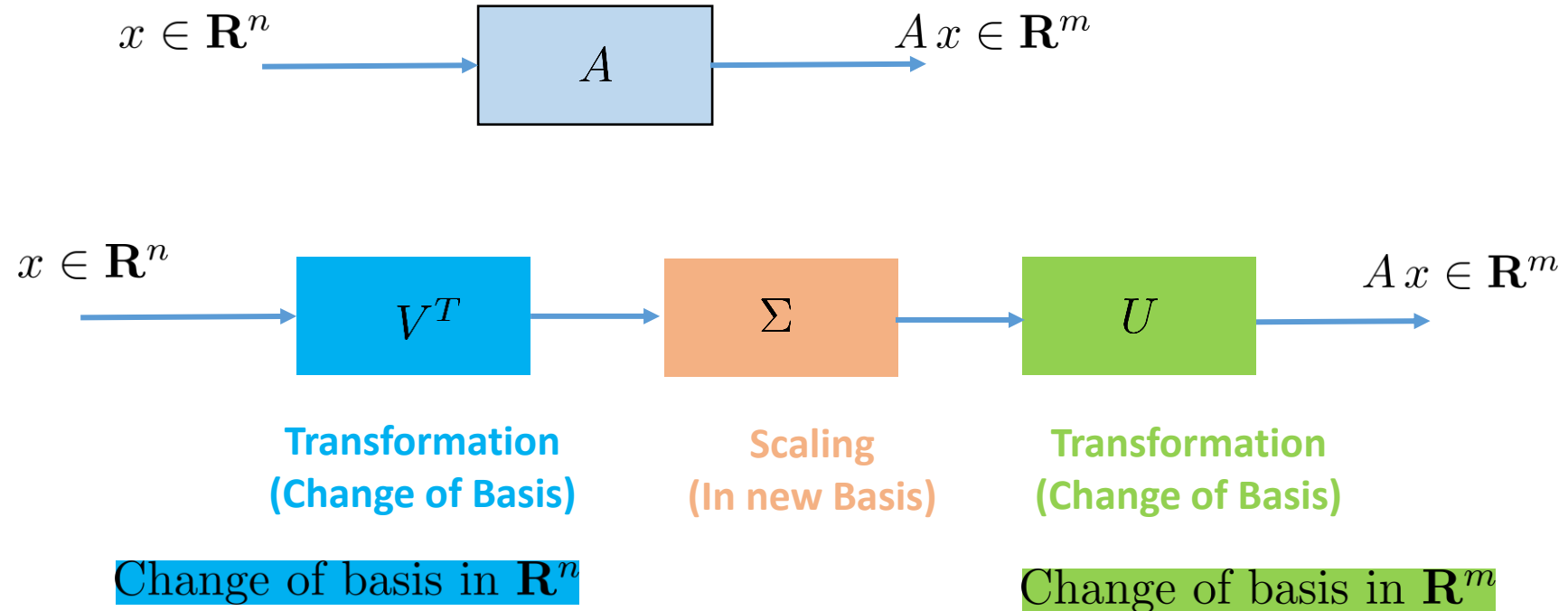
$$A = U \Sigma V^T$$

- EVD of  $AA^T$  gives  $U$  and first  $m$  singular values.
- EVD of  $A^T A$  gives  $V$  and first  $n$  singular values.
- $U$  and  $V$  are always orthogonal.
- SVD always exists.
- Singular values are non-negative, that is,

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_{\min(m,n)} \geq 0$$

# Singular Value Decomposition

## Geometric Interpretation

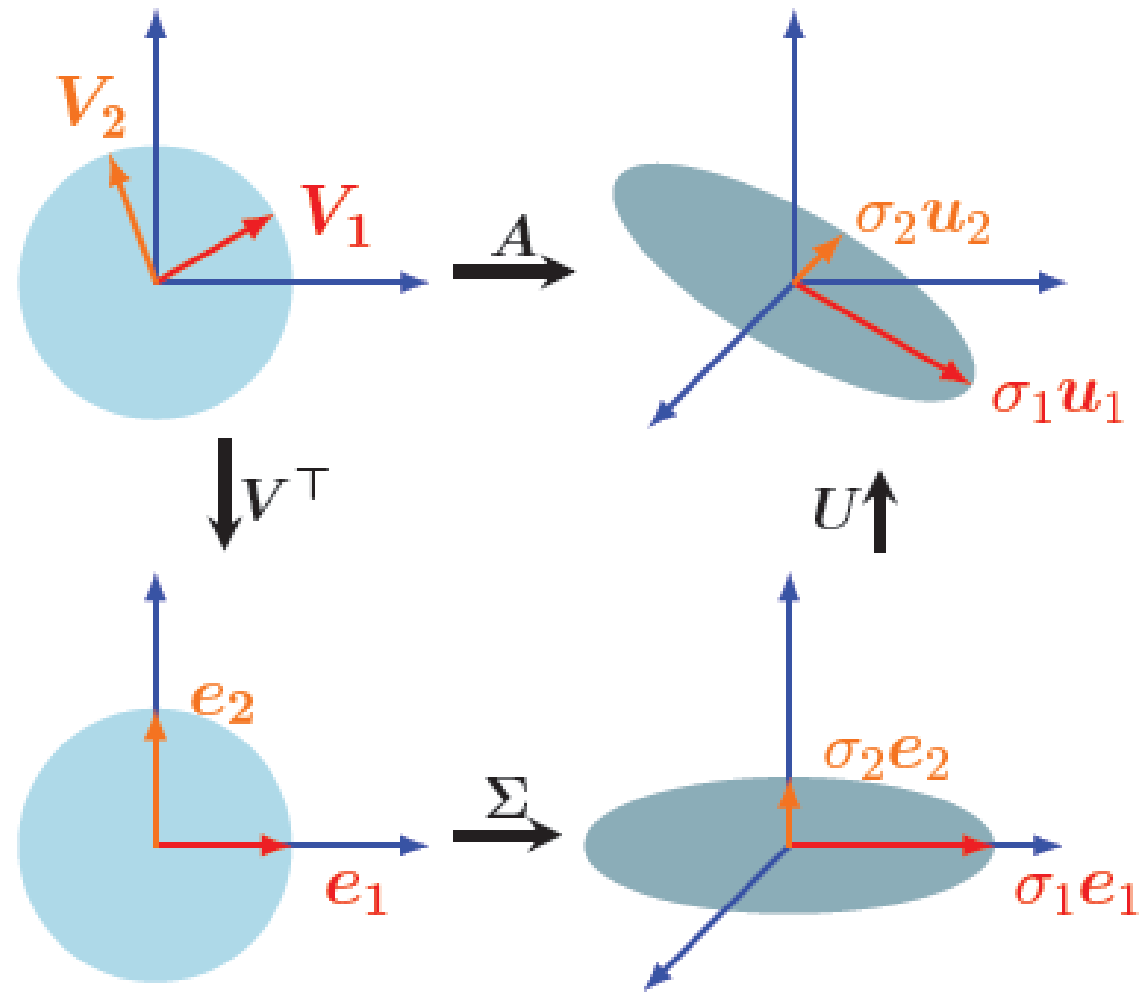


Scaling along the new basis by singular values.

- $m < n$  - Drop the last  $n - m$  basis (impact of columns of zeros in  $\Sigma$ )
- $m > n$  - Append  $m - n$  basis (impact of rows of zeros in  $\Sigma$ )

# Singular Value Decomposition

## Geometric Interpretation

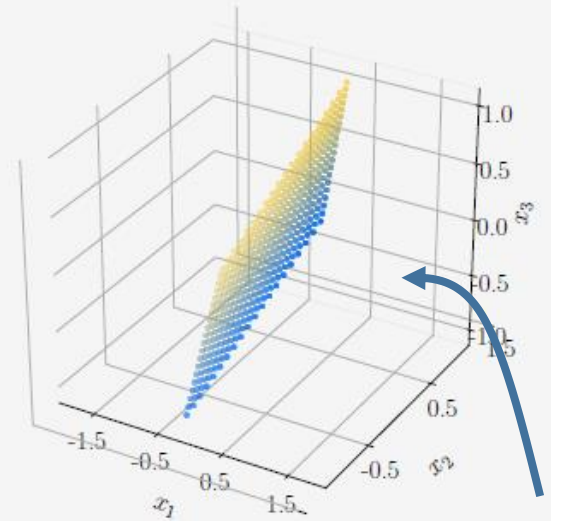
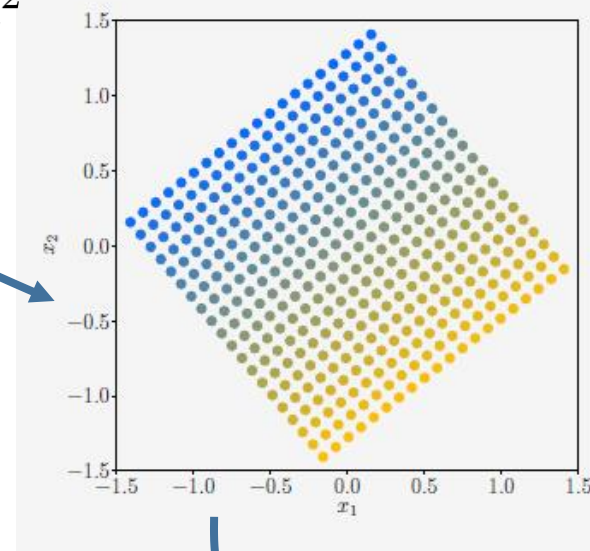
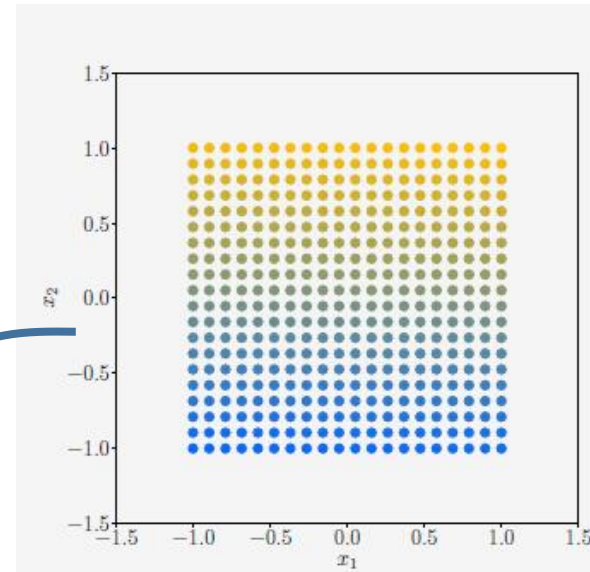


# Singular Value Decomposition

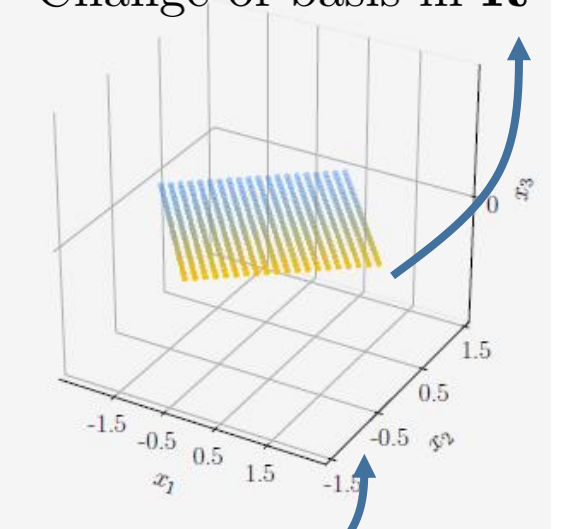
## Geometric Interpretation - Example

$$\begin{aligned} \mathbf{A} &= \begin{bmatrix} 1 & -0.8 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^\top \\ &= \begin{bmatrix} -0.79 & 0 & -0.62 \\ 0.38 & -0.78 & -0.49 \\ -0.48 & -0.62 & 0.62 \end{bmatrix} \begin{bmatrix} 1.62 & 0 \\ 0 & 1.0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -0.78 & 0.62 \\ -0.62 & -0.78 \end{bmatrix} \end{aligned}$$

Change of basis in  $\mathbf{R}^2$



Change of basis in  $\mathbf{R}^3$



- Append 1 more basis (impact of a row of zeros in  $\mathbf{\Sigma}$ )

# Singular Value Decomposition

## Rank of a Matrix:

- The rank of a matrix is equal to the number of non-zero singular values.

### How?

- Since  $A^T A$  and  $A$  have the same rank and we know that the rank of any square matrix equals the number of nonzero eigenvalues.

## Application Example – Rank Estimation:

*We use SVD for the estimation of rank while analyzing data. How?*

- Suppose that we have  $n$  data points  $a_1, a_2, \dots, a_n$ , all of which live in  $\mathbf{R}^m$ , where  $n$  is much larger than  $m$ . Let  $A$  be the  $m \times n$  matrix with columns  $a_1, a_2, \dots, a_n$ .
- Assume that the the data points satisfy some linear relations, such that  $a_1, a_2, \dots, a_n$  all lie in an  $r$  dimensional subspace of  $\mathbf{R}^m$ . Then we would expect the matrix  $A$  to have rank  $r$ .
- If the data points are obtained from measurements with errors, then the matrix  $A$  will probably have full rank  $m$ . But only  $r$  of the singular values of  $A$  will be large, and the other singular values will be close to zero.
- Using SVD, we can estimate an “approximate rank” of  $A$  by counting the number of singular values which are much larger than the others.



# Singular Value Decomposition

## Application: Matrix Approximation

- A matrix  $A \in \mathbf{R}^{m \times n}$  can be decomposed using SVD as

$$A = U \Sigma V^T = \sum_{i=1}^{\min(m,n)} u_i \sigma_i v_i^T$$

- If rank of a matrix is  $r \leq \min(m, n)$ , we can truncate the summation at  $r$

$$A = \sum_{i=1}^r u_i \sigma_i v_i^T$$

- Using SVD formulation, we can define  $k$  rank approximation of the matrix  $A$  by including first  $k$  singular vectors and associated singular values in the representation, that is,

$$A \approx \sum_{i=1}^k u_i \sigma_i v_i^T \quad (\text{k-rank approximation})$$

# Outline

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  - Application examples
- Column space and Null Space

# Column Space and Null Space

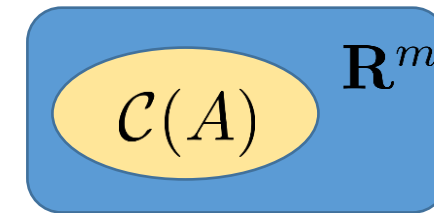
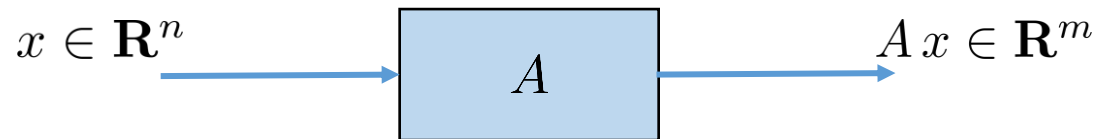
## Column Space:

- For a matrix  $A \in \mathbf{R}^{m \times n}$ , the column space, denoted by  $\mathcal{C}(A)$ , is the span of the columns of  $A$ .
- If  $a_1, a_2, \dots, a_n \in \mathbf{R}^m$  are the columns of  $A$ , column space is given by

$$\mathcal{C}(A) = \text{span}(a_1, a_2, \dots, a_n)$$

$$\mathcal{C}(A) = \{Ax \mid x \in \mathbf{R}^n\} \quad (\text{all possible linear combinations of columns of } A)$$

- In other words, column space is a linear transformation of every point in  $\mathbf{R}^n$ , that is,



- Consequently,  $\mathcal{C}(A)$  is the subspace of  $\mathbf{R}^m$ .
- What is the dimension of column space  $\mathcal{C}(A)$ ? Number of linearly independent columns of  $A = \text{rank}(A)$ .

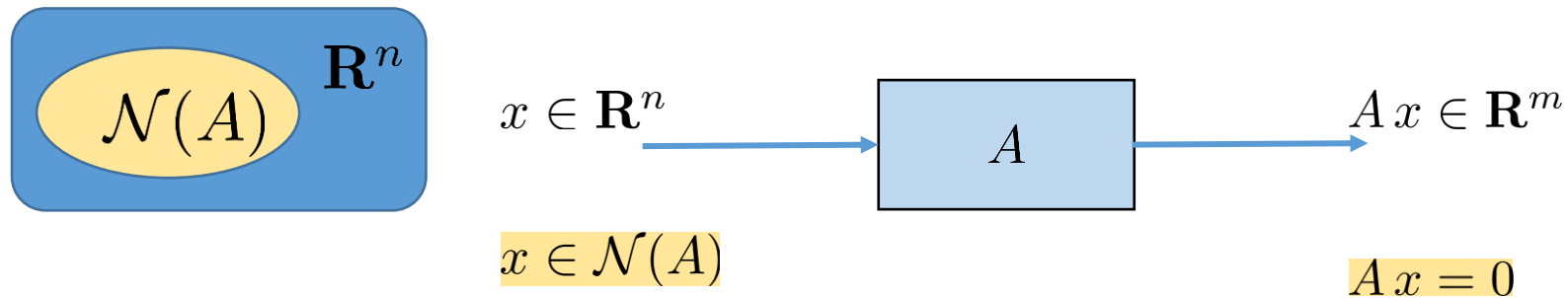
# Column Space and Null Space

## Null Space:

- For a matrix  $A \in \mathbf{R}^{m \times n}$ , the null space, denoted by  $\mathcal{N}(A)$ , is the subspace of  $\mathbf{R}^n$  such that

$$\mathcal{N}(A) = \{x \in \mathbf{R}^n \mid Ax = 0\} \quad (\text{all points that are mapped to zero by matrix } A)$$

- In other words, null space is an inverse linear transformation of  $0 \in \mathbf{R}^m$ .



- Nullity of the matrix, that is, the dimension of the null-space  $\mathcal{N}(A)$  is given by the following rank-nullity theorem (also known as rank+nullity theorem).

$$\text{rank}(A) + \text{nullity}(A) = \text{number of columns of } A$$

$$\dim(\mathcal{C}(A)) + \dim(\mathcal{N}(A)) = \text{number of columns of } A$$

# Column Space and Null Space

## Example:

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix}$$

- $m = 4, n = 3$
- $\mathcal{C}(A)$  is a subspace of  $\mathbf{R}^4$ .
- $\mathcal{N}(A)$  is a subspace of  $\mathbf{R}^3$ .

- Note that a third column is a sum of first two columns and therefore number of linearly independent columns is equal to 2.
- Consequently,  $\mathcal{C}(A)$  is a 2-dimensional subspace of  $\mathbf{R}^4$ .